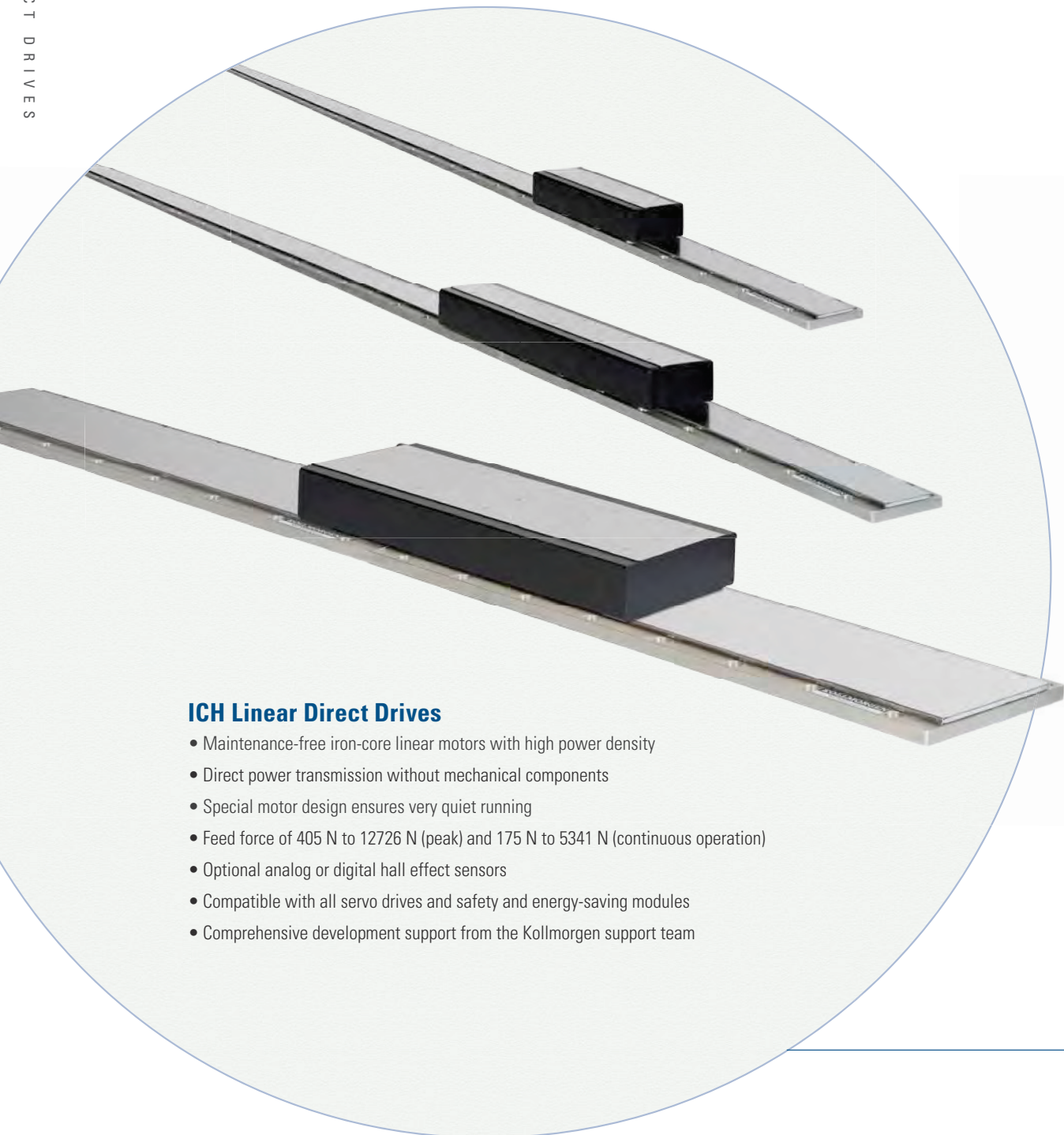


ICH Linear Direct Drives

Powerful Precision – As Much As You Want

Increase productivity and reduce operating costs – with the ICH linear motors from Kollmorgen you considerably improve overall equipment effectiveness. Cross the costs for maintenance work out of your calculations! Linear direct drives from Kollmorgen increase throughput compared with other drive systems by up to 40% and enable smaller, lighter machines with high energy efficiency due to their compact design.

ICH
L I N E A R
D I R E C T
D R I V E S



ICH Linear Direct Drives

- Maintenance-free iron-core linear motors with high power density
- Direct power transmission without mechanical components
- Special motor design ensures very quiet running
- Feed force of 405 N to 12726 N (peak) and 175 N to 5341 N (continuous operation)
- Optional analog or digital hall effect sensors
- Compatible with all servo drives and safety and energy-saving modules
- Comprehensive development support from the Kollmorgen support team

Wide Range of Speed – from $\mu\text{m/s}$ to km/h

Slower than $1 \mu\text{m/s}$ or faster than 5 m/s – the ICH linear motors from Kollmorgen move the load at all speeds precisely and with extremely low speed variations of $\pm 0.01\%$.

High System Dynamics Over 10 G

ICH linear motors are distinguished by their quick and powerful acceleration. The larger motors typically achieve values between 3 G and 5 G; smaller motors more than 10 G. The primary limiting factor is the machine's management system.

Low Power Fluctuation and High Synchronization

Iron-core linear motors boast high power density, but also a certain degree of cogging depending on the system. The motor design from Kollmorgen reduces cogging to a minimum. The ICH linear motors thus impress with their high power density with low power fluctuation and precise synchronization.

Precise Positioning to Fractions of a μm

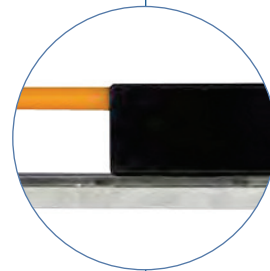
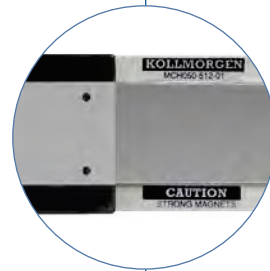
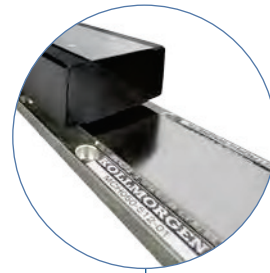
Positioning accuracy is limited by the resolution of the feedback system. In combination with the AKD servo drives from Kollmorgen you can develop linear drives that position quickly and precisely.

Unlimited Travel

The secondary parts can be supplied in lengths 64, 128, 256, and 512 mm and can be combined into travel distances as long as you wish.

Simple Drive Design with Few Parts

Drives with linear motors with no housing require fewer parts and are considerably simpler in structure than rotary motors. The ICH linear motors from Kollmorgen merely require an air gap of 0.8 mm – moreover, no critical adjustments are necessary.



ICH Linear Direct Drives

Feedback System

All brushless motors require a feedback system for the commutation. Kollmorgen offers digital hall effect sensors which are used in the same way as with rotary servo motors from the servo drive to the commutation. In applications with particularly demanding synchronization requirements, digital hall effect sensors are used and the servo drive supplies sinusoidal currents.

For exact position determination, linear encoders – whose signals are simultaneously used for the commutation – are frequently employed. The signals of the hall effect sensors can be used during the start phase in addition to the commutation.

Options

- Hall effect sensors (analog* or digital)
- Thermal overload protection PTC+KTY
- Different cable options

* In development

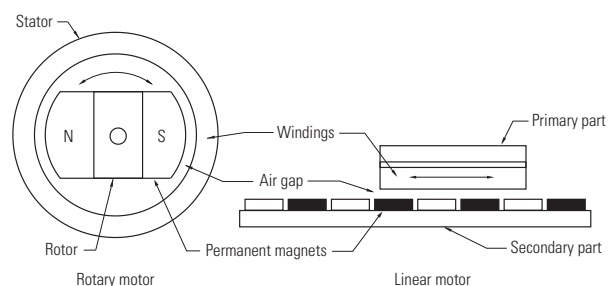
Applications Lurking Everywhere!

The ICH linear motors can be used in almost all motion tasks in many industries:

- Machine tools:
Tool positioning for drilling, milling, grinding, and laser cutting
- Semi-conductor industry:
Handling, checking and separating wafers, wire bonding, TAB, ion implantation, lithography
- Textile industry:
Tufting machines
- Metrology:
Coordinate measuring devices
- Assembly production:
Placement machinery, screen prints, glue dispensers, drilling and checking printed circuits
- Medical devices:
Patient positioning systems
- Preform injection molding machinery
- Plasma cutting machinery
- Flight simulators
- Acceleration slides, catapults

Functional Principle

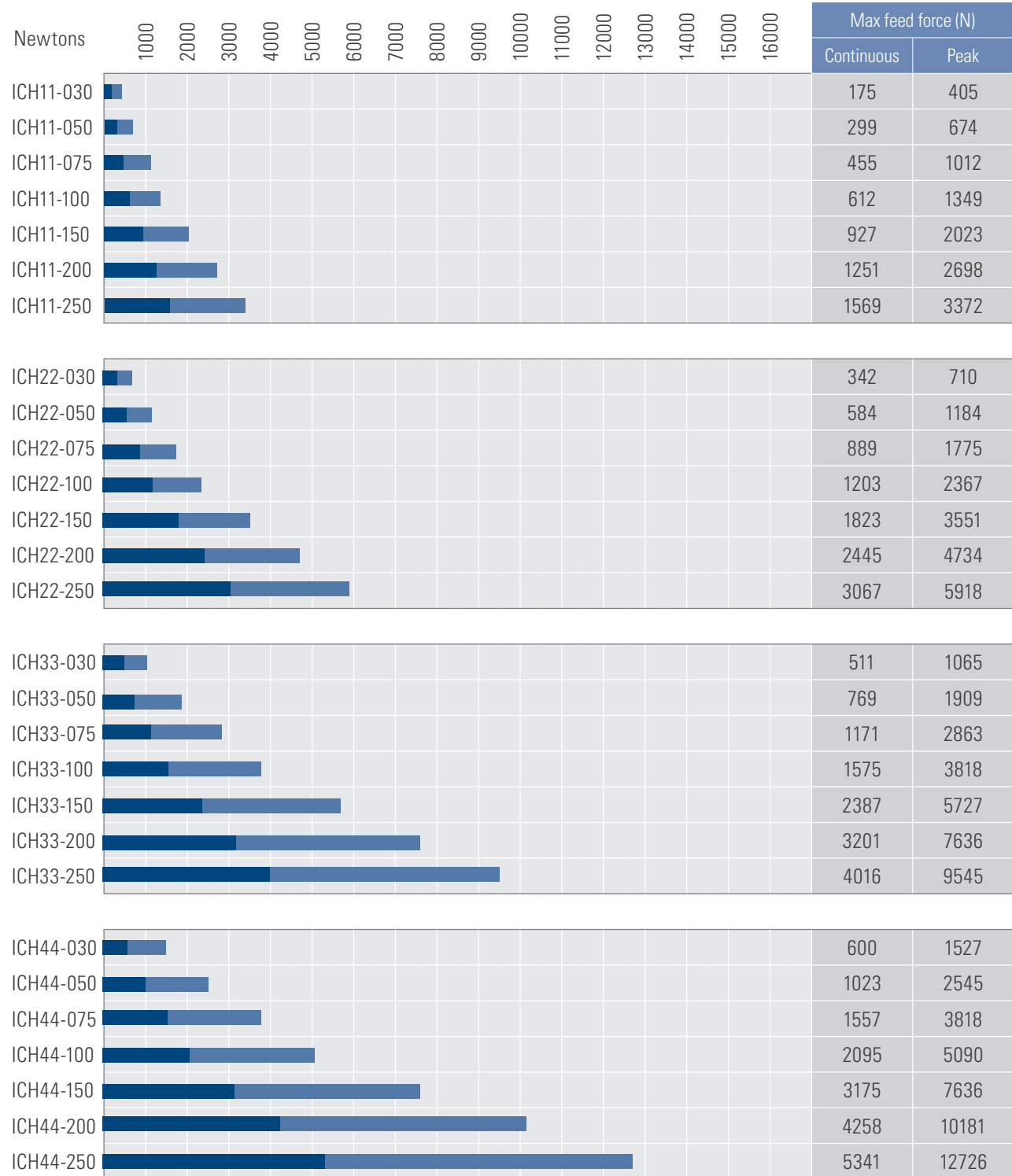
Linear motors function according to the same principle as conventional rotary motors. Rotor and stator are rolled out flat and are no longer connected together mechanically. They then form the two components "primary part" (stator, coil part) and "secondary part" (rotor, magnet section). The load is coupled directly to the moving part – usually the primary part – while the secondary part is fixed to the machine as a magnet guide. However, in special applications the primary part may be fixed while the secondary part moves. The functional principle remains the same.



ICH Linear Direct Drives

ICH Series Performance Overview

Feed force: ■ Continuous operation ■ Peak value



ICH Linear Direct Drives

Iron-core Linear Motors

Performance Data

Model	Winding ²⁾	Feed force [N]		Current [A]		Weight primary part [kg]	Secondary part type	Weight secondary part [kg/m]
		Peak	Continuous ¹⁾	Peak	Continuous			
ICH11-030	A1	405	175	8,9	2,9	2.5	MCH-030	5.4
	A5			15.5	5.0			
ICH11-050	A1	674	299	8.9	2.9	3.5	MCH-050	7.6
	A5			15.5	5.1			
ICH11-075	A1	1012	455	8.9	3.0	4.8	MCH-075	10.4
	A5			15.2	5.2			
ICH11-100	A1	1349	612	8.9	3.0	6.1	MCH-100	13.2
	A5			15.5	5.2			
ICH11-150	A1	2023	927	17.9	6.1	8.6	MCH-150	18.8
	A5			30.9	10.6			
ICH11-200	A1	2698	1251	30.6	10.6	11.2	MCH-200	24.4
	A5			53.0	18.3			
ICH11-250	A1	3372	1569	30.6	10.6	13.8	MCH-250	30.0
	A5			53.0	18.4			
ICH22-030	A1	710	342	8.9	2.8	4.9	MCH-030	5.4
	A5			15.5	4.9			
ICH22-050	A1	1184	584	8.9	2.9	6.8	MCH-050	7.6
	A5			15.5	5.0			
ICH22-075	A1	1775	889	17.9	5.9	9.3	MCH-075	10.4
	A5			30.9	10.2			
ICH22-100	A1	2367	1203	30.6	10.2	11.8	MCH-100	13.2
	A5			53.0	17.0			
ICH22-150	A1	3551	1823	30.6	10.4	16.8	MCH-150	18.8
	A5			53.0	17.9			
ICH22-200	A1	4734	2445	30.6	10.4	21.7	MCH-200	24.4
	A5			53.0	18.0			
ICH22-250	A1	5918	3067	30.6	10.5	26.7	MCH-250	30.0
	A5			53.0	18.1			
ICH33-030	A1	1065	511	8.9	2.8	7.2	MCH-030	5.4
	A5			15.5	4.9			
ICH33-050	A1	1909	769	30.6	8.8	10.2	MCH-050	7.6
	A5			53.0	15.2			
ICH33-075	A1	2863	1171	30.6	8.9	13.8	MCH-075	10.4
	A5			53.0	15.5			
ICH33-100	A1	3818	1575	30.6	9.0	17.5	MCH-100	13.2
	A5			53.0	15.6			
ICH33-150	A1	5727	2387	30.6	9.1	24.9	MCH-150	18.8
	A5			53.0	15.8			
ICH33-200	A1	7636	3201	45.9	13.8	32.2	MCH-200	24.4
	A5			79.5	23.8			
ICH33-250	A1	9545	4016	45.9	13.8	39.6	MCH-250	30.0
	A5			79.5	23.9			
ICH44-030	A1	1527	600	15.3	4.3	9.6	MCH-030	5.4
	A5			26.5	7.4			
ICH44-050	A1	2545	1023	15.3	4.4	13.5	MCH-050	7.6
	A5			26.5	7.6			
ICH44-075	A1	3818	1557	30.6	8.9	18.3	MCH-075	10.4
	A5			53.0	15.4			
ICH44-100	A1	5090	2095	30.6	9.0	23.2	MCH-100	13.2
	A5			53.0	15.6			
ICH44-150	A1	7636	3175	61.2	18.2	33.0	MCH-150	18.8
	A5			106.0	31.5			
ICH44-200	A1	10181	4258	61.2	18.3	42.7	MCH-200	24.4
	A5			106.0	31.7			
ICH44-250	A1	12726	5341	61.2	18.4	52.5	MCH-250	30.0
	A5			106.0	31.8			

1) Continuous feed force with maximum winding temperature 2) Other windings are possible – please ask us about them

ICH Coil Assembly Dimensions

Type	A [mm]	B [mm]	C [mm]
ICHxx-030	60	58.6 ±0.1	16
ICHxx-050	80	58.6 ±0.1	36
ICHxx-075	105	58.6 ±0.1	32
ICHxx-100	130	58.6 ±0.1	36
ICHxx-150	180	60.6 ±0.1	32
ICHxx-200	230	60.6 ±0.1	36
ICHxx-250	280	60.6 ±0.1	32

MCH Magnet Way Dimensions

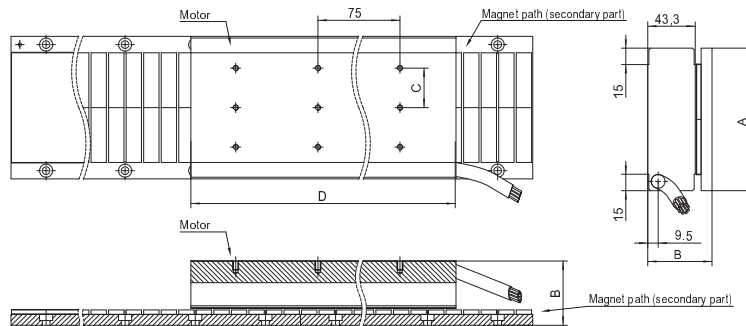
Type	F [mm]	G [mm]	H [mm]
MCH030-XXX-01	60	10	14.4
MCH050-XXX-01	80	10	14.4
MCH075-XXX-01	105	10	14.4
MCH100-XXX-01	130	10	14.4
MCH150-XXX-01	180	12	16.4
MCH200-XXX-01	230	12	16.4
MXH250-XXX-01	280	14	18.8

Primary Part Length

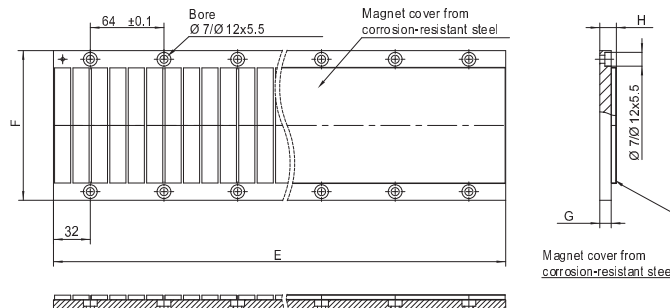
Type	D [mm]
ICH11-xxx	190
ICH22-xxx	375
ICH33-xxx	542
ICH44-xxx	718

Secondary Part Length

Type	E [mm]
MCHXXX-064-01	64
MCHXXX-128-01	128
MCHXXX-256-01	256
MCHXXX-512-01	512



Primary and secondary part assembly



Secondary part per segment

Model Nomenclature

ICH Linear Direct Drives

ICH 22 - 050 - A1 - TY - C1 - 0

ICH Series
Iron Core High Voltage

Design Length Identifier
11, 22, 33, 44

Coil Width
030, 050, 075, 100
150, 200, 250

Winding
A1, A5

Thermal Protection
TY PTC and KTY
(Standard)

Reserved for Customizations
00, 01, 02, etc.

Cable Options

Open ends

- C1 400 mm
- C2 200 mm
- C3 100 mm
- C4 1200 mm

With connected connector

- P1 400 mm
- P2 200 mm
- P3 100 mm
- P4 1200 mm

ICH Linear Direct Drives - Hall Sensors

(Order code for hall sensors when ordered separately)

HD - Y - Px

Hall-Option
HD = Digital
HA = Analog*

Winding Phase Connection
Y = Y (Star) Winding
D = Δ (Triangle) Winding

* In Preparation

Cable Options

Px - Cable with Sub-D connector

- P1 = 400 mm
- P2 = 200 mm
- P3 = 100 mm
- P4 = 1200 mm